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#### Name:

# APJ ABDUL KALAM TECHNOLOGICAL UNIVERSITY

B.Tech Degree S7 (S, FE) / S7 (PT) (S,FE) Examination May/June 2024 (2015 Scheme

#### **Course Code: ME407**

### **Course Name: MECHATRONICS**

Max. Marks: 100

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## Duration: 3 Hours

	PART A Answer any three full questions, each carries 10 marks.	Marks
a)	Explain the difference between static and dynamic characteristics of transducers.	(4)
a) b)	Compare the working of RTDs and thermocounles	(6)
(U)	Even by the working of an absolute optical encoder with a neat sketch	(6)
a)	Explain the working of an absolute optical encoder with a heat sketch.	(0)
b)	of 45 degrees.	(+)
a)	Explain the working of a synchro with neat diagram	(6)
b)	Differentiate between tandem center and float center DCVs	(4)
a)	Explain the working of a vane type hydraulic motor with a neat sketch.	(6)
b)	Compare the pneumatic and hydraulic actuation systems	(4)
	PART B Answer any three full questions, each carries 10 marks.	
a)	Explain the LIGA process with an example.	(6)
b)	Differentiate between CVD and epitaxy in MEMs manufacture.	(4)
a)	Explain the sequence of producing a deep channel using DRIE process.	(4)
* b)	Explain the working of a parallel plate capacitive MEMS accelerometer.	(6)
a)	Explain the working of a recirculating ball screw mechanism with neat sketches.	(6)
b)	Explain the different types of preloading with sketches	(4)
a)	Design a PLC ladder logic to operate two cylinders A,B in the sequence	(10)
	A1B1B0A0. Use solenoid operated DCVs for the cylinders.	
	PART C	
	Answer any four full questions, each carries 10 marks.	
a)	Explain the mathematical model of a spring-mass-damper system	(5)
b)	Explain the working of variable reluctance servo motor.	(5)

10 a) Explain the working of a harmonic drive with a sketch. (5)

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	b)	Explain the range sensing using triangulation method.	(5)
11	a)	Explain the working of a CCD camera sensor with neat sketches	(5)
	b)	Explain the difference between histogram sliding and histogram stretching.	(5)
12	a)	Explain the working of any two types of tactile sensors used in robotics.	(4)
	b)	Explain the working of a CID camera sensor. What are its advantages over CCD?	(6)
13	a)	Explain the engine management system of an automobile with a net block diagram	(10)
		including sensors and actuator connections and control strategy.	
14	(0	Evaluin the scheme of a nick and place report with a switchle control ladder logic	(10)

14 a) Explain the scheme of a pick and place robot with a suitable control ladder logic (10) and schematic.

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