Reg No.:	
	1100MRT30

APJ ABDUL KALAM TECHNOLOGICAL UNIVERSITY

B.Tech Degree S6 (S, FE) Examination January 2024 (2019 Scheme)



Course Code: MRT 308

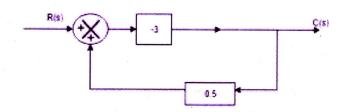
M	lax. M	larks:		ıam	e: COMPREHENS	IVE	COURSE WO	RK	Duration: 1Hour		
Instructions:			(1) Each question carries one mark. No negative marks for wrong answers (2) Total number of questions: 50 (3) All questions are to be answered. Each question will be followed by 4 possible answers of which only ONE is correct. (4) If more than one option is chosen, it will not be considered for valuation.								
1.		Which of the following law/rule can be used to determine the direction of rota motor?						of rota	tion of D.C.		
		a)	Lenz's law	b)	Faraday's law	c)	Coloumb's law	d)	Fleming's left- hand rule		
	2.	The	armature of D.C. g	gene	rator is laminated to						
		a)	Reduce the bulk	b)	Provide the bulk	c)	Insulate the core	d)	Reduce eddy current loss		
	3.	Bru	shes of D.C. machi	nes a	are made of						
		a)	Carbon	b)	Soft copper	c)	Hard copper	d)	All of above		
	4.	A s	ilicon controlled rea	ctifie	er (SCR) is a		••				
		a)	Uni junction device	b)	A device with three junction	c)	A device with four junction	d)	None of the above		
	5.	The	transformer ratings	s are	usually expressed in						
		a)	Volts	b)	Amperes	c)	kW	d)	kVA		
	6.										
		a)	Speed control	b)	High starting torque	c)	Both (a) and (b)	d)	None of these		
	7.	Which of the following motors is usually used in household refrigerators?									
		a)	D.C. shunt motor	b)	D.C. series motor	c)	Single-phase induction motor (split phase start or induction run	d)	Reluctance motor		
		_					motor)				
	8.				lc supply to the rotor of	of an	alternator is called	d a			
		a)	Convertor	b)	Exciter	c)	Inverter	d)	Rectifier		

9.	Universal motors are used in								
	a)	Conveyor	b)	Food mixer	c)	Elevator	d)	Refrigerator	
10	Inv	autan aanuauta							
10.		erter converts DC to AC	ы	AC to DC	(0)	DC to DC	d)	AC to AC	
	a)	DC to AC	U)	AC to DC	c)	DC to DC	u)	AC to AC	
11	Ho	w many AND gate	es are	required to realize	Y = CD	+ EF + G?			
	a)	4	b)	5	c)	3	d)	2	
12•		niversal logic gate owing is a univers		e which can be use ic gate?	d to gen	erate any logic f	unction	. Which of the	
	a)	OR	b)	AND	c)	XOR	d)	NAND	
13				ald be required for				_	
	a)	2	b)		c)	8	d)	3	
14	If A	A and B are the inp		a half adder, the c			-		
	a)	A AND B	b)	A OR B	c)	A XOR B	d)	A EX-NOR B	
15	The	e following switch	ing fu	nctions are to be in	nplemer	nted using a deco	der:		
*			•	$f2 = \sum m(2, 5, 9, 11)$	-				
				n of decoder will b	7				
	a)	2 to 4 line		3 to 8 line		4 to 16 line	d)	5 to 32 line	
16	,		,	e resulting flip-flop					
	a)	D flip-flop		S-R flip-flop		T flip-flop	d)	S-K flip-flop	
17	The	a hase current amr	dificat	ion factor β is give	n hv				
17	a)	IC/IB		IB/IC		IE/IB	d)	IB/IE	
	a)	IC/IB		IB/IC	C)	IL/IB	u)	IDIID	
18	Wł	nich of the followi	ng ten	minals does not bel	ong to t	he MOSFET?			
	a)	Drain	b)	Gate	c)	Base	d)	Source	
T									
19	Po	Power amplifier directly amplifies							
	<u>a</u>)	Voltage of signal	b)	Current of the signal	c)	Power of the signal	d)	All of the mentioned	
20	Wł	nich of the followi	ng ext	pression denicts Ba	rkhause	n criteria?			

				•		•			
	a)	$A\beta = 1$	b)	$A\beta = 0$	c)	$A\beta < 1 < A\beta$	d)	A β < 1	
21	Sm	allest change which	a se	nsor can detect is					
	a)	Resolution	b)	Accuracy	c)	Precision	d)	Scale	
22	Ac	ne-way valve that l	ets a	ir into the reservoir of	a co	mpressor, but does	n't le	et it out, is a	
	a)	Check valve	b)	Receiver valve	c)	Control valve	d)	Three way valve	
23		allest change which cision d) Scale	a se	nsor can detect is		a) Resolutio	on b)	Accuracy c)	
•	a)		b)		c)		d)		
24	Sta	rters are used in ind	uctio	on motor because					
	a)	Its starting torque is high) It is run against heavy load	c)	It cannot run in reverse direction	d)	Its starting current is five times or more than its rated current	
25	The	scientific principle	that	makes hydraulic syste	ems	possible is			
	a)	Pascal's principle.	b)	Boyle's law	c)	Bernoulli's principle	d)	The fluid flow principle	
26	A variable reluctance stepper motor is constructed of poles.					material with salient			
	a)	Paramagnetic	b)	Ferromagnetic	c)	Diamagnetic	d)	Non-magnetic	
27	A s	tepping motor is a _		device.					
	a)			Electrical	c)	Analogue	d)	Incremental	
28	Wh	at does an Encoder	do?						
			3.						
*	a)	Senses mechanical motion	b)	Provides information concerning position, velocity and direction	c)	Converts analog into digital information	d)	All of the above	
29	Wh	ich type of motion	is tra	nsmitted by hydraulic	actu	ators?			
	a)	linear motion	b)	rotary motion	c)	both a and b	d)	none of the above	
30	Wh	ich energy is conve	rted	into mechanical energ	y by	the hydraulic cylin	nders	?	
	a)	hydrostatic	b)	hydrodynamic	c)	electrical	d)	none of the	

31	Mi	Microprocessor can function as the CPU of a computer called a										
	a)	Personal Computer	b)	Microcomputer	c)	Super Computer	d)	Desktop Computer				
32	Wh	nich of the following	g par	t of the microproce	essor is c	closely related to r	egister	?				
	a)	Processor	b)	Memory	c)	ALU	d)	BUS				
33	Ma	Maximum memory which can be interfaced with a 8085 microprocessor.										
	a)	32kB	b)	64kB	c)	128kB	d)	256kB				
34	An	An example of one byte instruction is										
	a)	CALL 2500H	b)	ADD B	c)	IN 80H	d)	MVI A, 24H				
35	In a	In an intel 8085A, which is the first machine cycle of an instruction?										
	a)	An op-code fetch cycle	b)	A memory read cycle	c)	A memory write cycle	d)	An I/O read cycle				
36	_	is the only non-vectored interrupt in 8085 microprocessor.										
	a)	TRAP	b)	RST 5.5	c)	INTR	d)	RST 7				
37		Which general register or general register pair is incremented/decremented by 2 during PUSH and POP instructions?										
	a)	H-L	b)	D-E	c)	Stack Pointer	d)	Program Counter				
38	CALL instruction is a instruction.											
	a)	4 bytes	b)	2 bytes	c)	1 bytes	d)	3 bytes				
39	The	e instruction, CMP t	о со	mpare source and o	lestinati	on operands it per	forms					
*	a)	addition	b)	subtraction	c)	division	d)	multiplication				
40	In g	In general, the destination operand of an instruction can be										
	a)	memory location	b)	register	c)	immediate data	d)	memory location and register				
41	Wh	What is the effect of feedback in the overall gain of the system?										
	a)	Increases	b)	Decreases	c)	Zero	d)	No change				
42	The	overall transfer fur	nctio	n of two blocks in j	parallel	are:						

- Sum of b) Product of a) Difference of d) Division of individual gain individual gain individual gain individual gain 43 Effect of feedback on sensitivity is minimum in: a) Open loop b) Closed loop control c) None d) **Both** control system system 44 The closed system has higher than open loop control system, this implies increased speed of response. Gain b) Bandwidth c) Frequency d) Speed
- The closed loop gain of the system shown in the given figure is



- a) -9/5 b) -6/5 c) 6/5 d)
 46 The transient response, with feedback system,
 - a) Rises slowly b) Rises quickly c) Decays slowly d) Decays quickly

9/5

- The type 0 system has _____ at the origin.
- a) No pole b) Net pole c) Simple pole d) Two poles
- The position and velocity errors of a type-2 system are
 - a) constant, b) constant, infinity c) zero, constant d) zero, zero constant
- In case of type-1 system steady state acceleration is
- a) Unity b) Infinity c) Zero d) 10
- Which of the following is the best method for determining the stability and transient response?
 - a) Root locus b) Bode plot c) Nyquist plot d) None of the above