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Name:

APJ ABDUL KALAM TECHNOLOGICAL UNIVERSITY

B.Tech Degree S6 (S, FE) / S4 (PT) (S) Examination January 2024 (2019 Scheme)

Course Code: EET306

		Course Code: EET306		
		. Course Name: POWER ELECTRONICS		
Ma	x. N	farks: 100 Duration: 3	Hours	
		Graph sheet may be provided PART A		
		Answer all questions, each carries 3 marks.	Marks	
1		Explain the peripheral effects of power electronic converters. How can it be remedied?	(3)	
2		Write short notes on wide band gap devices.	(3)	
3		Explain with relevant sketch, the concept of phase control employed in phase controlled rectifiers.		
4		Explain the effect of freewheeling diode in phase controlled rectifier circuit.		
5		With neat circuit diagram and waveforms explain the working of a single phase AC voltage controller feeding an RL load.		
6		Explain the advantages of internal voltage control method employed in inverters.		
7		Explain the current limit control employed in dc-dc converters.		
8		Derive the relationship between input and output voltages in a step down chopper.	(3)	
9		Explain the advantages of an electric drive.	(3)	
10		Explain the components of load torque.	(3)	
•		PART B Answer one full question from each module, each carries 14 marks.		
		Module I		
11	a)	Explain in detail, the different turn on methods of an SCR.	(10)	
•	b)	Explain the switching characteristics during turn off of an IGBT.	(4)	
		. OR		
12	a)	Explain the two transistor analogy of an SCR.	(8)	
	b)	Explain the reverse recovery characteristics of a power diode.	(6)	
		Module II		
13	a)	Explain with a neat circuit diagram the working of a half controlled bridge	(9)	

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rectifier with freewheeling diode feeding RLE load. Also draw the output voltage, output current, freewheel diode current and source current waveforms. Derive the expression for average output voltage.

b) A single phase full converter is supplied from 230V, 50 Hz source. The load consists of load R= 10Ω and a large inductance so as to render the load current constant. For a firing angle delay of 30°, determine (a) average output voltage (b) average output current (c) average value of thyristor current.

OR

Explain the working of a three phase half controlled bridge converter feeding (14)

RLE load in continuous conduction mode with a neat circuit diagram and output voltage waveform. Assume the firing angle to be 30°. Show the conducting devices. Derive the output voltage equation.

Module III

- 15 a) With neat circuit diagram and waveforms, explain the working of a single phase (7) full bridge inverter feeding RL load.
 - b) Explain with a neat circuit diagram and waveforms the working of a single phase (7) capacitor commutated current source inverter with R load.

OR

Explain the 120° conduction mode of operation of three phase voltage source (14) inverter with output voltages indicating the devices conducting in each state.

Module IV

- 17 a) With a neat circuit diagram, explain a four quadrant chopper. (7)
 - b) With a neat circuit diagram, explain the working of a step up chopper. Also (7) derive the relationship between input and output voltages.

OR

- 18 a) With neat circuit diagram, explain the working of boost regulator. Also derive (7) the design expression for L and C.
 - b) The buck regulator has an input voltage of 12V. The required average output voltage is 5V at R = 500 Ω and the peak-to-peak output ripple voltage is 20 mV. The switching frequency is 25 kHz. If the peak-to-peak ripple current of inductor is limited to 0.8 A, determine (a) the duty cycle d, (b) the filter inductance L, (c) the filter capacitor C.

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Module V

- 19 a) Explain with neat circuit diagram and waveforms the working of a single phase (7) fully controlled DC drive.
 - b) A dc chopper is used for regenerative braking of a separately excited DC motor. (7) The dc supply voltage is 400V. The motor has ra=0.2 Ω and torque constant to be 1.2Vs/rad. The average armature current during regenerative braking is kept constant at 300A with negligible ripple. For a chopper with duty cycle of 60 %, determine (i) power returned to DC supply(ii) minimum and maximum possible braking speeds (iii) speed during regenerative braking

OR

- 20 a) Explain the stator voltage control method of speed control of a three phase (7) induction motor drive.
 - b) Explain the block diagram of an electric drive (7)
