### 06000MR301012301

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Name:

# APJ ABDUL KALAM TECHNOLOGICAL UNIVERSITY

Fifth Semester B.Tech Degree (S, FE) Examination December 2023 (2015 Scheme)

### Course Code: MR301 Course Name: LINEAR CONTROL SYSTEMS

Max. Marks: 100 Duratio		1: 3 Hours	
	PART A Answer all the questions, each carry 5 marks.	Marks	
ľ	Explain closed loop control system with an example.	(5)	
2	What are the basic elements used for modelling mechanical rotational system?	(5)	
	Write the torque balance equations for these elements.		
3	Define the parameters that specify the performance of control systems in time	(5)	
	domain.		
4	Construct a Routh array and determine the stability of system characterized by the	(5)	
	equation $9s^5-20s^4+10s^3-s^2-9s-10=0$ .		
5	Give an example for transportation lag in a system.	(5)	
6	Recall a non-minimum phase system.	(5)	
7	Enumerate any five applications of control system in mechatronics.	(5)	
8	Cite any five features of lead compensator.	(5)	

#### PART B

### Answer any three questions, each carry 10 marks.

9

Draw a signal flow diagram and evaluate the closed loop transfer function of the (10) given system.



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Determine the torque \*-voltage analogous equations of the given mechanical (10) rotational system. Also draw its analogous electrical circuit.



- 1) Obtain the response of an over-damped second order system for a unit step signal. (10) Plot its waveform.
- 12 A unity negative feedback system is characterized by an open loop transfer (10) function G(s)= K/S(S+10). Calculate gain K, so that the system has a damping ratio of 0.5. Determine peak overshoot and time at peak overshoot for a unit step signal.
- 13 The open loop transfer function of a unity feedback system is (10)  $G(s)=K(s+9)/s(s^2+4s+11)$ . Sketch the root locus of the system.

#### PART C

#### Answer any two questions, each carry 15 marks.

- 14 Draw Bode plot and obtain gain cross over frequency for the given transfer (15) function. G(s)=20/s(1+3s) (1+4s).
- 15 The open loop transfer function of a unity feedback system is given by (15)  $G(s)=1/s^2(1+s)$  (+2s). Sketch the polar plot. Determine the gain margin and phase margin.
- 16 Discuss the different types of controllers employed in control system with (15) necessary equation.
- 17

Describe any two examples of closed loop control systems with its block diagram. (15)

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Page 2 of 2

10