

APJ ABDULKALAM TECHNOLOGICAL UNIVERSITY
08 PALAKKAD CLUSTER

Q. P. Code : CES0819222-I

(Pages: 3)

Name:

Reg. No:



SECOND SEMESTER M.TECH. DEGREE EXAMINATION APRIL 2019

Branch: Electronics & Communication Engineering Specialization: Communication Engineering & Signal Processing

08EC 6222 ESTIMATION & DETECTION

Time: 3 hours

Max. Marks: 60

Answer all six questions.

Modules 1 to 6: Part 'a' of each question is compulsory and answer either part 'b' or part 'c' of each question.

Q.no.	Module 1	Marks
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|-----|--|---|
| 1.a | Determine the Maximum-Likelihood decision rule associated with the following messages. | 3 |
|-----|--|---|

$$m_1: p(z/m_1) = \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{z^2}{2}\right)$$

$$m_2: p(z/m_2) = \frac{1}{2\sqrt{2\pi}} \exp\left(-\frac{z^2}{8}\right)$$

Answer b or c

- | | | |
|---|--|---|
| b | State and explain MAP Decision criterion. | 6 |
| c | Determine the decision rule associated with the following conditional probabilities: | 6 |

$$m_1: p(z/m_1) = \begin{cases} e^{-z} & \text{for } z \geq 0 \\ 0 & \text{otherwise} \end{cases}$$
$$m_2: p(z/m_2) = \begin{cases} e^{z-1} & \text{for } z \leq 1 \\ 0 & \text{otherwise} \end{cases}$$

with $P\{m_1\} = 0.5$, $P\{d_2|m_1\} = 0.1$ using

- (1) Neyman-Pearson criterion
- (2) Probability of error criterion.

Q.no.	Module 2	Marks
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- 2.a State and explain MIN-MAX Criterion. 3

Answer b or c

- b Determine the Baye's decision rule associated with the following conditional probabilities: 6

$$m_1: p(z/m_1) = \frac{1}{2} e^{-|z|}$$

$$m_2: p(z/m_2) = e^{-2|z|}$$

The costs are given by $C_{11}=C_{22}=0$; $C_{12}=1$; $C_{21}=2$ and $P\{m_2\}=0.75$.

- c Explain BAYES RISK criterion with example. 6

Q.no.	Module 3	Marks
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- 3.a Write a short note on Integrating optimum receiver. 3

Answer b or c

- b If the observation is formed by adding an independent zero-mean, unit-variance Gaussian random variable to each component of the signal vector : $z = s + n$, where n and s are I -dimensional vectors and

$$s_1 = \begin{bmatrix} 0 \\ 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix} \text{ and } s_2 = \begin{bmatrix} s_1 \\ s_1 \\ s_1 \\ \vdots \\ s_1 \end{bmatrix}$$

Obtain an optimum decision for this problem. Find the expression for sufficient statistic $l(z)$ and the decision region.

- c With neat block diagram, explain matched filter receiver. 6

Q.no.	Module 4	Marks
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- 4.a State and explain Baye's estimation criterion. 3

Answer b or c

- b Obtain an expression for linear minimum variance estimator $\hat{\theta}_{LMV}$ for the two dimensional observation of a scalar parameter given by

$$Z = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \theta + \begin{bmatrix} n_1 \\ n_1 \end{bmatrix}$$

where the statistical parameters are $\mu_\theta=0$; $V_\theta=V$; $\mu_n=0$; $V_n=\sigma^2 I$.

- c Briefly explain linear mean squares method.

6

Q.no.	Module 5	Marks
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- 5.a Explain maximum likelihood estimation.

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Answer b or c

- b Develop a linear unbiased minimum error variance algorithm for state estimation for the given vector equation

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$$X(k+1) = \Phi(k+1) x(k) + \Gamma(k)w(k)$$

$w(k)$ is the input noise and zero mean white noise process with co-variance $\text{cov} \{w(k), w(j)\} = V_w(k) S_k(k-j)$

- c Show that for any unbiased estimator of a scalar θ , the conditional variance is bounded by

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$$\text{var}\{\hat{\theta} / \theta\} \geq \{E \partial / \partial \theta (\ln p(z/\theta))\}^2\}^{-1}$$

Define an efficient estimate. Prove that the maximum likelihood estimate for the parameter θ from the set of observations

$$Z_i = \theta + n_i \quad i=1,2,3,\dots,I$$

n 's are identically distributed Gaussian random variable with zero mean and σ^2 variance.

Q.no.	Module 6	Marks
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- 6.a What is concept of sufficient statistics?

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Answer b or c

- b Briefly explain minimum variance unbiased estimation.
c Write short note on sensitivity and error analysis.

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