

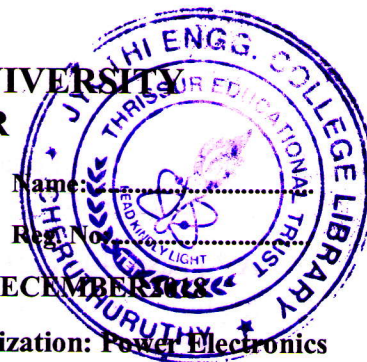
**APJ ABDULKALAM TECHNOLOGICAL UNIVERSITY**  
**08 PALAKKAD CLUSTER**

Q. P. Code :PE 0821118(A)

(Pages: 2)

Name: .....

Reg.No: .....



**THIRD SEMESTER M.TECH. DEGREE EXAMINATION DECEMBER 2018**

Branch: Electrical and Electronics

Specialization: Power Electronics

**08EEE7211 (A) Special Electrical Machines and Drives**

Time:3 hours

Max.marks: 60

**Answer all six questions.**

**Modules 1 to 6:**Part 'a' of each question is compulsory and answer either part 'b' or part 'c' of each question.

<b>Q.no.</b>	<b>Module 1</b>	<b>Marks</b>
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1.a	Compare the constructional feature Hybrid stepper motor with normal PM stepper motor	3
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**Answer b or c**

b	With the help of relevant waveforms, explain the static and dynamic characteristics of stepper motor	6
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c	Explain with the help of relevant block diagram on the microprocessor control of stepper motor.	6
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<b>Q.no.</b>	<b>Module 2</b>	<b>Marks</b>
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2.a	What are the merits and demerits of a classic converter for SRM control	3
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**Answer b or c**

b	With the help of circuit diagram and operational waveforms, explain the following of a typical Dump-C converter for SRM control (i) Operation (ii) merits and demerits.	6
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c	Explain single pulse and PWM modes of SRM. How current limits in the motor and inverter components are controlled.	6
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<b>Q.no.</b>	<b>Module 3</b>	<b>Marks</b>
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3.a	Explain the basic principle of synchronous reluctance motor	3
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**Answer b or c**

- b** With the help of phasor diagram, derive the torque equation of Synchronous reluctance motor **6**
- c** A 3 phase, 400V, 50 Hz, star connected synchronous reluctance motor with negligible armature resistance, has direct and quadrature axis reactance values are given as  $X_{sd}=8$  ohms and  $X_{sq} = 2$  ohms respectively. For a Load torque of 80 N-m, Calculate (i) load angle (ii) line current. Neglect rotational losses **6**

<b>Q.no.</b>	<b>Module 4</b>	<b>Marks</b>
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|-----|--|---|
| 4.a | Explain the principal of operation of BLDC motor | 3 |
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**Answer b or c**

- b** Compare the principle of position detection using optical and Hall elements in Permanent magnet brushless DC motor. **6**
- c** Compare mechanical and Electronic commutators in PM-BLDC motors **6**

<b>Q.no.</b>	<b>Module 5</b>	<b>Marks</b>
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|-----|--|---|
| 5.a | With suitable diagram explain about BLDC square wave motor | 4 |
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**Answer b or c**

- b** Explain different modes of PWM control of a BLDC motor. **8**
- c** Explain the microprocessor-based control of BLDC motor with suitable block diagram **8**

<b>Q.no.</b>	<b>Module 6</b>	<b>Marks</b>
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|-----|---------------------------------------|---|
| 6.a | Describe the phasor diagram of a PMSM | 4 |
|-----|---------------------------------------|---|

**Answer b or c**

- b** Obtain the equation for torque of Permanent magnet synchronous motor **8**
- c** Explain the principle of vector control for PMSM **8**