B4B0102

Reg No.:

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Duration: 3 Hours

Name:

APJ ABDUL KALAM TECHNOLOGICAL UNIVERSIT FOURTH SEMESTER B.TECH DEGREE EXAMINATION, JULY 2017

Course Code: EE202

Course Name: SYNCHRONOUS AND INDUCTION MACHINES (H	EE)
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Max. Marks: 100

PART A

		Answer all questions. Each carries 5 marks.			
1		Enumerate various methods for minimising harmonics in alternators.	(5)		
2		What are the different methods of finding the voltage regulation of an alternator.	(5)		
3		Describe the slip test method for finding the X_d and X_q of synchronous machines.	(5)		
4		Explain the constructional details of a synchronous motor.	(5)		
5		Differentiate between the phenomenon cogging and crawling of an induction motor.	(5)		
6		List the various methods adopted for braking of an induction motor.	(5)		
7		Compare induction generator with synchronous generator.	(5)		
8 With a sketch describe the principle of working of a shaded pole motor.					
		PART B	12		
		Answer any two questions. Each carries 10 marks.			
9	a)	Explain various types of armature winding of an alternator.	(5)		
	b)	Find the distribution and pitch factor of a 3Φ , 4 pole, 24 slots alternator having its armature coils short pitched by one slot.	(5)		
10		A 0.5 MVA, 1.1KV, 50 Hz, 3Φ , star connected alternator has R_a and X_s per phase as 0.1 Ω and 1.5 Ω respectively. Find its voltage regulation at different power factor of (i) unity (ii) 0.9 lag and (iii) 0.8 lead at full load.	(10)		

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A 220V, 6 pole, 50 Hz, star connected alternator gave the following test results: -(10)Field current 0.2 0.4 0.6 0.8 1 12 14 18 22 26 3 31

Fleid current	0.2	0.4	0.0	0.0	1	1.2	1.4	1.0	2.2	2.0	3	5.4
in A												
Open circuit	29	58	87	116	146	172	194	232	261	284	300	310
line voltage in	(
Volts												
ZPF test line	-	-	-	-	-	0	29	88	140	177	208	230
voltage in												
volts												
SCC in A	6.6	13.2	20	26.5	32.4	40	46.3	59				

Find % voltage regulation at full load current of 40A at power factor 0.8 lag by (i) m.m.f method (ii)ZPF method. $R_a=0.06 \Omega$ /phase.

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PART C

Answer any two questions. Each carries 10 marks.

(10)Explain the two reaction theory of salient pole alternator. 12 Describe the constructional features of 3Φ slip ring induction motor. (5)13 a) b) A 6 pole, 50 Hz, 3Φ , slip ring induction motor, the rotor resistance and the reactance (5)at stand still per phase are 0.3 and 1.5 Ω respectively. The e.m.f between the slip rings on open circuit is 175V. Calculate (i) Slip (ii) rotor e.m.f/phase (iii) rotor frequency and reactance when the motor runs at a speed of 950 r.p.m. (5)What are the various methods of synchronisation of alternators. 14 a) Explain the effect of excitation on armature current and power factor of a (5) b) synchronous motor and hence deduce the V and inverted V curves. PART D Answer any two questions. Each carries 10 marks. 15 a) What are the different types of starters used for starting a 3Φ induction motor. (5)b) A 3Φ induction motor has a short circuit current 5 times of full load current at 5% (5)slip. Determine the starting torque and starting current if the impressed voltage is reduced to 60% of the normal voltage by using starting resistance starter. The full load current and torque are 10 A and 10 Nm respectively. (10)16 a) Explain the principle of operation of an induction generator. (5)b) Describe the double field revolving theory of a 1 Φ induction motor. Draw the circle diagram of a 3Φ , 20 hp,400V,50Hz star connected induction motor (5) 17 a) with the following test data: -400V 9A $\cos \Phi = 0.2$ No load test 200V 50A $\cos \Phi = 0.4$ block rotor test Stator and rotor copper losses are divided equally in the block rotor test. From the above circle diagram obtain (a) line current (b) power factor (c) slip (d) (5) b) efficiency at full load.

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