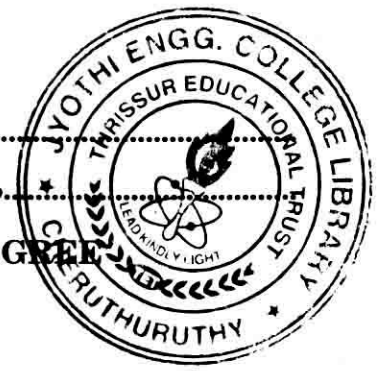


**C 61490**

(Pages : 2)

Name.....

Reg. No.....



**SIXTH SEMESTER B.TECH. (ENGINEERING) DEGREE  
EXAMINATION, APRIL 2014**

(2009 Scheme)

**ME/PTME/AM 09 605—COMPUTER INTEGRATED MANUFACTURING**

(Regular/Supplementary/Improvement)

Time : Three Hours

Maximum : 70 Marks

**Part A**

*Answer all the questions.  
Each question carries 2 marks.*

1. How do you determine the spindle speed and the feed of machining ?
2. Describe any *four* important G-codes used in part programming.
3. What are the check surface modifiers used in APT ?
4. What are the different operations performed by ASRS ?
5. List out the benefits of FMS.

(5 × 2 = 10 marks)

**Part B**

*Answer any four questions.  
Each question carries 5 marks.*

6. Explain different tool holding devices used in CNC machines.
7. Explain the various steps involved in computer aided part programming.
8. Distinguish between point-to-point and contour programming in NC system.
9. Discuss different types of AGVs.
10. Write short notes on :
  - (a) Barcode technology ; and
  - (b) Optical character recognition.
11. Discuss different types of drives used in robot control.

(4 × 5 = 20 marks)

**Turn over**

**Part C**

*Answer section (a) or section (b) of each question.*

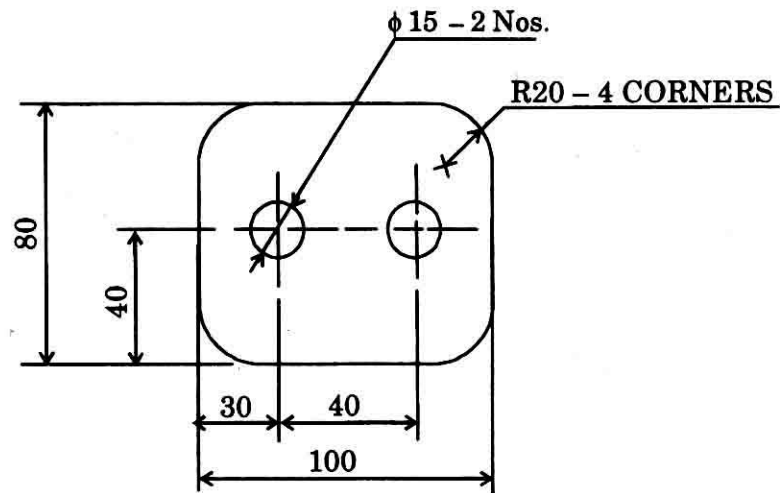
*Each question carries 10 marks.*

12. (a) Describe briefly the important design considerations of CNC machine tools.

*Or*

- (b) Discuss the features of CNC machine tools.

13. (a) Write an APT part programme of the job given in the figure below.



*Or*

- (b) What are G-codes and M-codes in part programming? Explain with suitable example.

14. (a) Briefly describe the vehicle management and safety system used in AGVs.

*Or*

- (b) Explain briefly, group technology.

15. (a) Explain briefly the material handling and storage systems used in FMS.

*Or*

- (b) Discuss different classification of robot sensors.

(4 × 10 = 40 marks)