

SIXTH SEMESTER B.TECH. (ENGINEERING) DEGR EXAMINATION, JUNE 2011

EC 04 603—CONTROL SYSTEMS

(2004 admissions)

Time: Three Hours

Maximum: 100 Marks

Answer all questions.

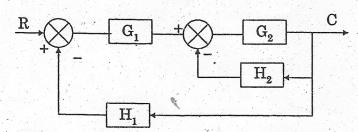
- I. (a) State and explain the properties of Laplace transforms.
 - (b) Explain the advantages and applications of signal flow graphs.
 - (c) Explain the performance of feedback control systems.
 - (d) Explain the concept of stability with an example.
 - (e) Explain the properties of z-transform Prove any two.
 - (f) Explain the cyclic and multi-rate sampling.
 - (g) Define and explain:
 - (i) State Variables.
 - (ii) State vector.
 - (iii) State space.
 - (h) Explain the Laplace transform approach to the solution of state equations.

 $(8 \times 5 = 40 \text{ marks})$

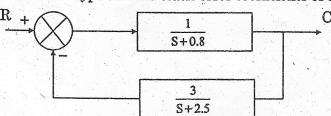
II. (a) Derive Mason's gain formula. Explain the steps.

Or

(b) Find $\frac{C(s)}{R(s)}$ for the system shown in figure:



III. (a) Determine the type and the static error coefficients of the system given in figure:



Turn over

(b) Apply Routh's criterion to test the stability of the system described by:

$$s^5 + 0.5s^4 + 3s^3 + 1.5s^2 + 0.5s + 0.5 = 0.$$

IV. (a) Prove all the properties of z-transform.

Or

- (b) Write short notes on:
 - (i) Bilinear transformation.

(7 marks)

(ii) Sample and hold.

(8 marks)

V. (a) Explain the state space representation of Discrete time systems.

Explain the adventages and applications? Or ninfox?

- (b) Write technical notes on:
 - (i) State transition matrix.

(7 marks)

(ii) State space models.

(8 marks)

 $[4 \times 15 = 60 \text{ marks}]$